# **MANNESMANN** REXROTH

# Variable Displacement Pump A7V

Series 5.1, for open circuits Axial piston unit, bent axis design

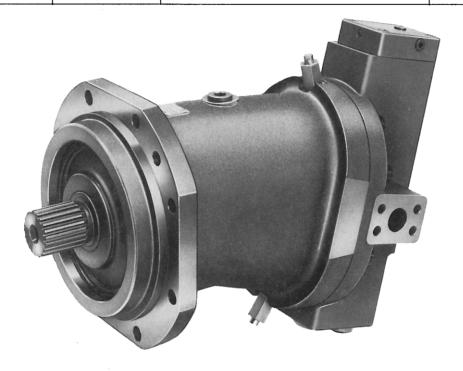
RE 92210/01.84

Brueninghaus Hydromatik

Sizes 250...1000

High pressure range up to 400 bar

replaces 01.82



## Description

Variable displacement pump,, axial piston bent axis design, for hydrostatic transmissions in open circuits.

The flow is proportional to the drive speed and the displacement and is steplessly variable at constant drive speed.

Comprehensive programme of control devices for every control and regulating function.

### Special Features of Series 5.1

New, simplified high performance rotary group with enhanced technical data and well-proven spherical control area.

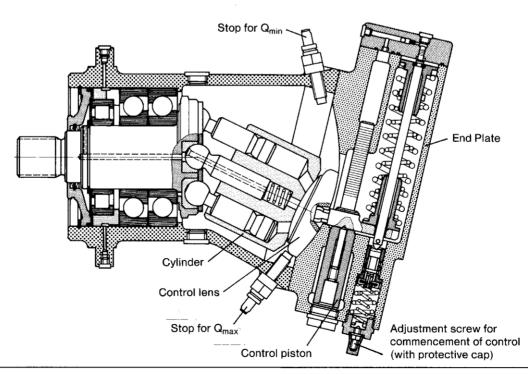
Section - Variable displacement Pump A7V, Series 5.1, with Constant Horsepower Control LV

Robust roller bearings for high loads.

Hydrostatic unloading of bearings possible for continous pressures up to 350 bar.

Operation on both mineral and fire-resistant fluids.

Improved port plate design and compact construction reduces noise level by 5 dBA.



with pressure cut-off bill-on for LV. EL and HD Constant pressure control. F remote controlled (order sequence value and subject experience) Displacement V <sub>2</sub> min - V <sub>2</sub> max) Displacement V <sub>2</sub> min - V <sub>2</sub> min - V <sub>2</sub> max) Displacement V <sub>2</sub> min - V <sub>2</sub> max Displacement V <sub>2</sub> min - V <sub>2</sub> max Displacement V <sub>2</sub> min - V <sub>2</sub> m	Variable Displacer	ment Pump A7V, S	eries 5.	1							
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Displacement V <sub>g min</sub> - V <sub>g min</sub>	0 – 1000 cm³	1000									Auxiliary Equipment
Control Device  Constant horsepower	Displacement V <sub>g m</sub>	<sub>lin</sub> –V <sub>g max</sub> )							<u> </u>		
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Shaft End  Splined shaft DIN 5480	with handwheel)										
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pressure control  Aux. Equipment stroke limiter, mech.  EL Electrical control with pressure cut-off with pressure cut-off  HD Hydraulic control, pressure related  remote controlled  without pressure cut-off  with pressure cut-off							•	•	•		
Control  Aux. Equipment stroke limiter, mech.  EL Electrical control  with pressure cut-off	DR Constant pressure										<del></del>
EL Electrical control  with pressure cut-off  with pressure cut-off  HD Hydraulic control, pressure related  with pressure cut-off		Aux Fauir-s-									
control  with pressure cut-off  HD Hydraulic control, pressure related  with pressure cut-off	El Electrical	Aux. Equipment				off				•	<u> </u>
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MA Manual control	MA Manual contro	ol								<u> </u>	<u>-</u>

# **Technical Data**

### Operating Pressure Range - Inlet Side

Absolute pressure at port S (suction inlet) 0.8 bar

Pabs max (see case drain pressure)

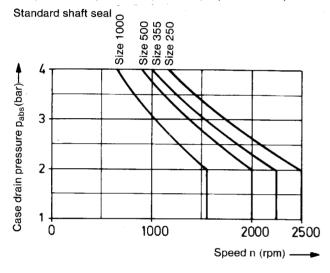
### **Operating Pressure Range - Outlet Side**

Pressure at port A or B <sub>-</sub> p<sub>N</sub> = 350 bar Rated pressure. p<sub>max</sub> = 400 bar Peak pressure. (Pressure data to DIN 24312)

For pulsating pressures in excess of 315 bar we recommend the use of the models with splined shaft (DIN 5480).

#### **Case Drain Pressure**

Max. permissible case drain pressure The permissible pressure is, however, dependent on speed.

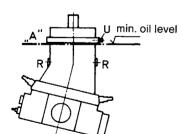


A higher case drain pressure is possible by using mechanical seals (see RE 94104). When ordering, please indicate in clear text: "with mechanical seal".

Mounting Position: Optional. The pump housing must always be filled with oil. When mounting within a tank the plug must be removed from ports R and one of these ports must be at the top.

### Note:

With vertical mounting, with drive shaft pointing upwards: The min. oil level must not fall below line "A".



When mounting within a tank, the plugs must be removed from ports R.

When mounting outside the tank, the pump must be bled at port U prior to commissionina.

With manual control MA:

The axis of the handwheel must be horizontal (because of position indicator on handwheel).

### **Direction of flow**

clockwise rotation	anti-clockwise rotation
S to B	S to A

# **Hydraulic Fluid**

#### **Operating Viscosity Range**

For optimum efficiency and service life, we recommend that the operating viscosity (at operating temperature) be selected in the range

= optimum operating viscosity 16 ... 36 mm<sup>2</sup>/s

as referred to tank temperature (open circuits).

### **Limits of Viscosity Range**

For extreme operating conditions, the following values apply:

10 mm<sup>2</sup>/s ν<sub>min</sub> =

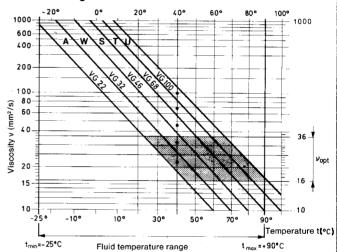
for short periods with a max.permissible leakage oil temperature of 90 °C.

1000 mm<sup>2</sup>/s  $v_{\text{max}} =$ 

for short periods upon cold start.

For detailed information on the selection of hydraulic fluids on mineral oil base and application conditions, please see our catalogue sheet RE 90220 prior to project design.

#### Selection Diagram



### Notes on the Selection of the Hydraulic Fluid

For correct selection of the hydraulic fluid, it is necessary to know the operating temperature in the tank (open circuits) in relation to the ambient temperature.

The hydraulic fluid should be selected so that within the operating temperature range the operating viscosity lies within the optimum range vopt (see selection diagram, shaded section). We recommend that the higher viscosity grade be selected in each case.

Example: At an ambient temperature of X °C, the operating temperature in the circuit is 60 °C. In the optimum operating viscosity range (vopt, shaded section), this corresponds to viscosity grades VG 46 or VG 68; VG 68 should be selected.

Important: The leakage oil temperature is influenced by pressure and speed and is always higher than the tank temperature, but may not be higher than 90 °C.

If is not possible to keep within the above conditions because of extreme operating parameters or high ambient temperature, we recommend flushing the bearings via port U.

Flushing	Size	250	355	500	1000
fluid flows	Q <sub>So</sub> I/min	12,5	16.	25	40

Temperature of the flushing fluid  $\leq$  tank temperature.

### **Filtration**

Recommended filtration 10  $\mu m$ . Coarser filtration of 25 -40 µm is possible, but longer component life will be achieved using 10 µ filtration due to lower component wear.

# **Technical Data**

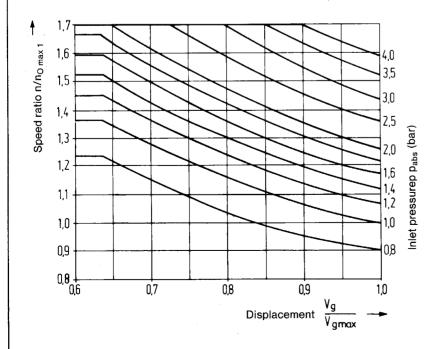
(theoretical values, without consi	dering mechhyd. and volumetric effici	ency)					
Size		Size		250	355	500	1000
Displacement		V <sub>g max</sub>	cm <sup>3</sup>	250	355	500	1000
•		V <sub>g min</sub>	cm <sup>3</sup>	0	0	0	0
Max. speed1)	at V <sub>g max</sub>	n <sub>0 max 1</sub>	rpm	1500	1320	1200	950
	at $V_g < V_{g max}$ (see diagram)	n <sub>0 max 2</sub>	rpm	2050	1800	1640	1300
Max. perm. speed (speed limit) with (see diagram below)	n increased inlet pressure p <sub>abs</sub>	n <sub>0 max peri</sub>	<sub>n</sub> rpm	2500	2240	2000	1600
Max. flow <sup>2</sup> )	at n <sub>0 max 1</sub> (V <sub>g max</sub> )	Q <sub>0 max 1</sub>	l/min	364	455	582	921
	at $n_{0 \text{ max } 2}$ ( $V_g < V_{g \text{ max}}$ )	Q <sub>0 max 2</sub>	I/min	318	396	509	807
Max. power	at Q <sub>0 max 1</sub>	P <sub>0 max 1</sub>	kW	218	273	350	554
(△p = 350 bar)	at Q <sub>0 max 2</sub>	P <sub>0 max 2</sub>	kW	191	238	306	485
Torque (△p = 100 bar)	at V <sub>g max</sub>	M N	m/100 bar	397,5	564,5	795	1590
Max. torque (△p = 350 bar)	at V <sub>g max</sub>	M <sub>max</sub>	Nm	1391	1975	2782	5565
Moment of inertia about the dirve a	xis	J	kgm²	0,088	0,160	0,270	0,824

<sup>1)</sup> The values shown are valid with an absolute pressure at suction inlet S and when operated on mineral oil. When idling, overspeeding by 50 rpm is permissible at  $n_{0\,\text{max}\,2}$ 

# Calculation

Flow	$Q = \frac{V_g \cdot n \cdot \eta_v}{1000}$	[I/min]	V <sub>g</sub> = geom. displacement per rev. (cm³)	
			$\Delta p$ = differential pressure (bar)	
Deixo Torquo	$_{\rm M}$ $=$ 1,59 · $\rm V_g$ · $\Delta p$	[Nm]	n = speed (rpm)	
Drive Torque	$\frac{100 \cdot \eta_{\rm mh}}{100 \cdot \eta_{\rm mh}}$	[14111]	η <sub>ν</sub> = volumetric efficiency	
			η <sub>mh</sub> = mech-hyd. efficiency	
Drive Dawer	B _ 2π·M·n _ M·n _ Q·Δp	_ [kW]	η, = overall efficiency	
Drive Power	$r = \frac{1}{60000} = \frac{1}{9549} = \frac{1}{600 \cdot \eta}$	- [[]	$[\eta_t = \eta_v \cdot \eta_{mh}]$	
	·	•		

Calculation of Inlet Pressure  $p_{abs}$  at Suction Inlet S and of Reduction in Displacement at Increased Speeds.



### Example:

Given: Size 500 Drive speed 1345 rpm

Drive speed 1345 (pill

Solution: speed ratio

 $\frac{n}{n_{o \text{ max 1}}} = \frac{1345}{1200} = 1,12$ 

pressure p<sub>abs</sub> at suction inlet S

gives an inlet pressure of  $p_{abs}$  = 1.4 bar at full swivel ( $V_{g max}$ ). If for example free flow is only possible with  $p_{abs}$  = 1 bar, the displacement must be reduced to

84.5%.

Note: Max. perm. speed  $n_{O\ max.\ perm.}$  (speed limit) Min. and Max. perm. suction pressure at port S.

<sup>&</sup>lt;sup>2</sup>) Calculated with a volumetric efficiency of 97%. By increasing the inlet pressure (p<sub>abs</sub> > 1 bar), speeds can be increased up to "max. perm. speed (speed limit)". (See diagram).

# Constant Horsepower Control LV

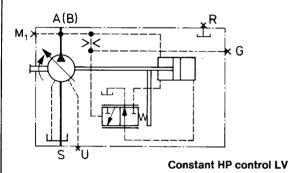
The constant HP control regulates flow in relation to pressure, thereby maintaining hydraulic power constant.

(Provided that the drive speed is constant).

Operating pressure acts on a pilot piston, causing is to press on a set of springs. If the hydraulic force exceeds the spring force, pilot oil is fed to the adjusting piston, which swivels the pump back to a smaller angle and therefore a smaller flow.

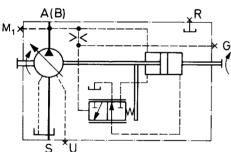
### Start of control: 50 bar min.

Summation HP control possible by means of throttles via port G.



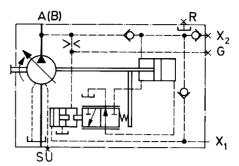
# **Auxiliary Equipment: Stroke Limiter**

By means of a mechanical or hydraulic stroke limiter, the max. displacement can be infinitely varied or limited. Adjustment range from  $V_{g max}$  to  $V_{g min}$ .



Constant HP control LV with mechanical stroke limiter

Size		250	355	500	-
Spindle revolutions	U <sub>S max</sub>	21,25	24	25	_



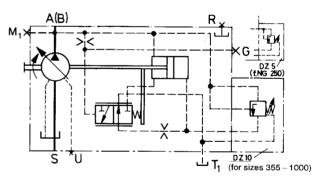
Constant HP control LV with hydraulic stroke limiter

A pilot pressure (port X<sub>1</sub>) of at least 10 % of the operating pressure is required for the hydraulic stroke limiter. Max. permissible pressure at port  $X_1 = 200$  bar (for all sizes). If it is required to limit the flow at an operating pressure 50 bar, then a boost pressure of min. 50 bar must be applied at port X2.

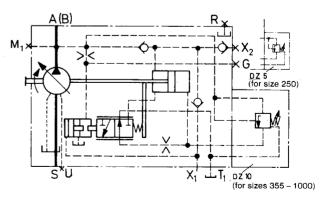
### **Auxiliary Equipment: Pressure Cut-Off**

The pressure cut-off is a constant pressure control superimposed on the constant HP control, and is carried out by means of a sequence valve. When the set maximum pressure is reached (control range up to 315 bar), the valve opens and the flow is automatically reduced (to Q = O).

The sequence valve is mounted directly on the pump.



Constant HP control LV with pressure cut-off



**Constant HP control LV** with pressure cut-off and hydraulic stroke limiter

# **Continuous Operation in Zero Position**

see constant pressure control DR

# Connections (Pump)

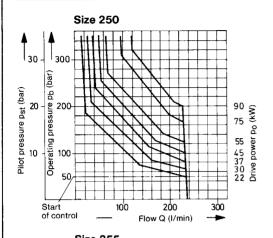
A, B	service lines	T <sub>1</sub>	pilot oil return line
S	suction line	R	air bleed
G	port of summation HP control	U	flushing port (for flushing of bearings)
$X_1$ $X_2$	pilot pressure remote control pressure	М	gauge connection (operating pressure)

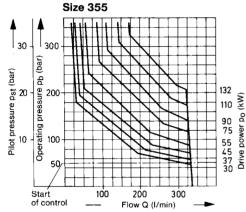
Variable Displacement Pump A7V, Series 5.1

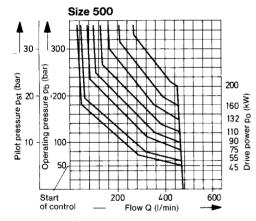
Approximate values at speed n = 980 rpm Fluid temperature t = 50 °C

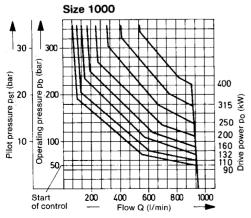
# Q-p-Characteristics for LV

# without Pressure Cut-Off







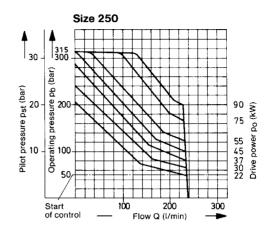


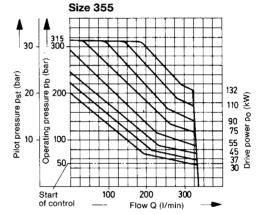
Conversion to speeds n (rpm) other than no

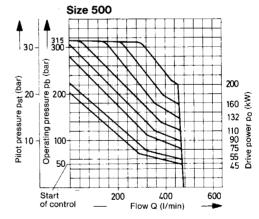
Drive power

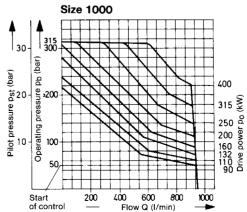
Flow  $Q_n = Q$ 

### with Pressure Cut-Off







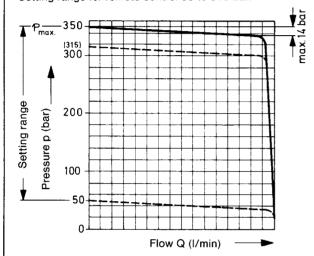


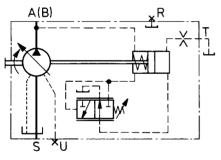
The constant pressure control maintains the pressure in a hydraulic system within its control range in spite of changing pump flow requirements. The variable pump supplies only the volume of fluid required by the services. Should operating pressure exceed the set pressure, the pump is automatically swivelled back to a smaller angle and the deviation in control corrected.

The required pressure is set either direct at the pump (valve built-in, standard model) or at the separate sequence valve for the model with remote control.

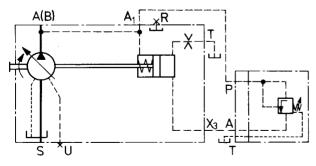
Setting range from 50 to 350 bar.

Setting range for remote control 50 to 315 bar.





Constant pressure control DR (valve built-in)



Constant pressure control DR (remote controlled)

Note: Port T from the sequence valve must be piped separately to tank (cooler).

### **Parallel Operation**

For parallel operation each individual pump requires its own sequence valve.

### Remote control

### Order sequence valve and subplate separately:

Sequence valve for size 250 DZ5DP2-1X/315YS021

(part No. 154869)

Sequence valve for sizes

355-1000

DZ10DP2-12/315YMS049

(part No. 154972)

Subplate for size 250

G 115/1 (Part No. 153138)

Subplate for sizes 355-1000 G 461/1 (Part No. 154363)

### The max. single pipe length should not exceed 5 m.

Note: A pressure relief valve installed in the system for protection of the max. pressure must be set 20 bar above the setting of the constant pressure control.

### **Auxiliary Equipment: Stroke Limiter**

The max, displacement can be steplessly limited between  $V_{q max}$  and  $V_{q min}$  by means of a mechanical stroke limiter. For details see control device LV.

### **Continuous Operation in Zero Position**

Zero stroke operation without flushing of housing short periods < 10 min long periods ~ 50 % duty				
max. perm.	max.perm.	max. perm.	max. perm.	
pressure	tank tem-	pressure	tank tem-	
	perature		perature	
p <sub>max</sub> (bar)	t <sub>max</sub> ( °C)	p <sub>max</sub> (bar)	t <sub>max</sub> ( oC)	
315	50	200	50	

Zero stroke operation with flushing of housing via long-term Port U.

max. perm.	max. perm.
pressure	tank tem-
	perature
p <sub>max</sub> (bar)	t <sub>max</sub> (°C)
315	50

	Size	250	355	500	1000	_
flow	Q <sub>sp</sub> I/min	12,5	16	25	40	_

Temperature of flushing fluid ≤ tank temperature

### Connections (Pump)

service lines

S suction line

ports for remote control valve

Т pilot oil return line

R air bleed

flushing port

(for flushing of bearings)

Variable Displacement Pump A7V, Series 5.1

# **Electrical Control EL**

The electric control permits stepless and programmable adjustment of the pump displacement. Adjustment is proportional to the solenoid force, i.e. the strength of current. The control force on the control piston is generated by a sole-

For the control of the proportional valve, a DC supply of 24 V between 250 and 750 mA is required.

Control is from  $V_{g \ min}$  to  $V_{g \ max}$ .

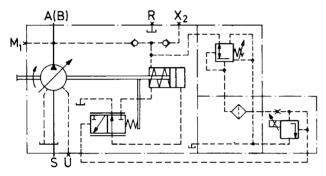
Pilot pressure range 10 - 45 bar.

The pilot pressure increase over the complete control range is 35 bar.

Start of control at approx. 250 mA \(\text{\rightarrow}\)10 bar pilot pressure. 

### Insulation to DIN 40050 IP65

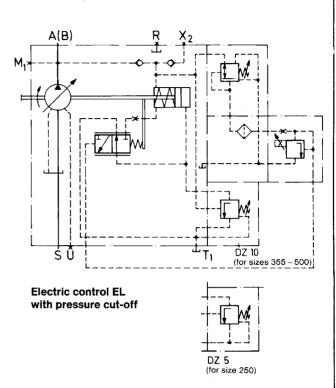
The necessary control oil is taken from the high pressure circuit, a minimum operating pressure of 50 bar being required. If necessary, an auxiliary pressure of 50 bar should be applied at port X2.



**Electric Control EL** 

# **Auxiliary Equipment: Pressure Cut-Off**

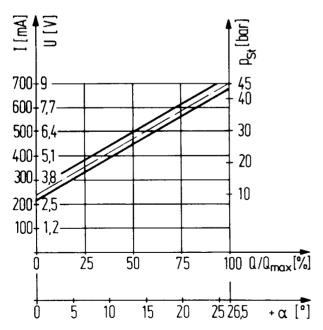
For description see control device HD.



# **Continuous Operation in Zero Position**

For details see constant pressure control DR

### **Control Curve**



Electronic control is by means of amplifier type VT 2000 S 20 to Rexroth catalogue sheet RE 29911.

### Connections (Pump)

A, B service lines suction line

 $X_2$ remote control pressure

 $T_1$ pilot oil return line (tank)

R air bleed

gauge connection

(operating pressure)

U flushing port

(for flushing of bearings)

# Hydraulic Control, Pressure Related, HD

The hydraulic control, pressure related, permits the stepless adjustment of the pump displacement in relation to pilot pressure. Adjustment is proportional to the pilot pressure at port X<sub>1</sub>.

When using the HD control as 2-position control ( $V_{g\ min}$  to V<sub>g max</sub>), the pilot oil pressure on port X<sub>1</sub> must not exceed 40

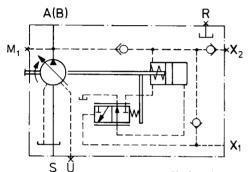
Adjustment is from  $V_{g min}$  to  $V_{g max}$ .

The increase in pilot pressure over the complete control range (min - max) is 10 bar.

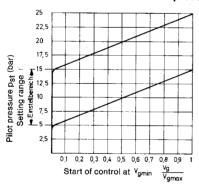
The setting range for start of control is between 5 and 15 bar (other values on enquiry).

The necessary control oil is taken from the high pressure circuit, and a minimum operating pressure of 40 bar is required. If necessary apply pilot pressure of 40 bar at port X2.

There is no continuous consumption of pilot oil, but leakage of approx. 0.5 I/min must be taken into consideration.



Hydraulic control, pressure related, HD

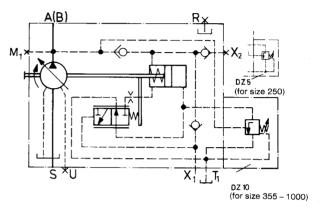


#### **Additional Function: Pressure Cut-Off**

The pressure cut-off serves to limit the flow as a function of the high pressure so that a predetermined operating pressure is not exceeded.

This function is carried out by a sequence valve. On reaching the set maximum pressure (setting range up to 315 bar), the valve opens and the flow is automatically reduced (to Q = 0).

The sequence valve is mounted directly on the pump.



Hydraulic control, pressure related, HD with pressure cut-off

# **Continuous Operation in Zero Position**

For details see constant pressure control DR

### Connections (Pump)

A, B service lines

S suction line

 $X_1$ pilot pressure

 $X_2$ remote control pressure

 $T_1$ pilot oil return line (tank)

R air bleed

M₁ gauge connection

(operating pressure)

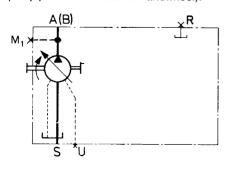
flushing port

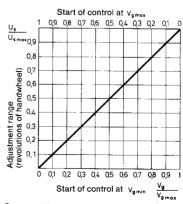
(for flushing of bearings)

# Manual Control, MA

By turning the handwheel, a piston is moved in an axial direction by means of a threaded spindle. A carrier pin moves the control lens on its sliding plane, thus permitting stepless variation of the pump displacement in the range  $\rm V_{g\ min}$  to  $\rm V_{g}$ max or conversely.

Mounting position: Axis of handwheel horizontal (because of pump position indicator in handwheel).





### Connections (Pump)

A, B service lines

S suction line

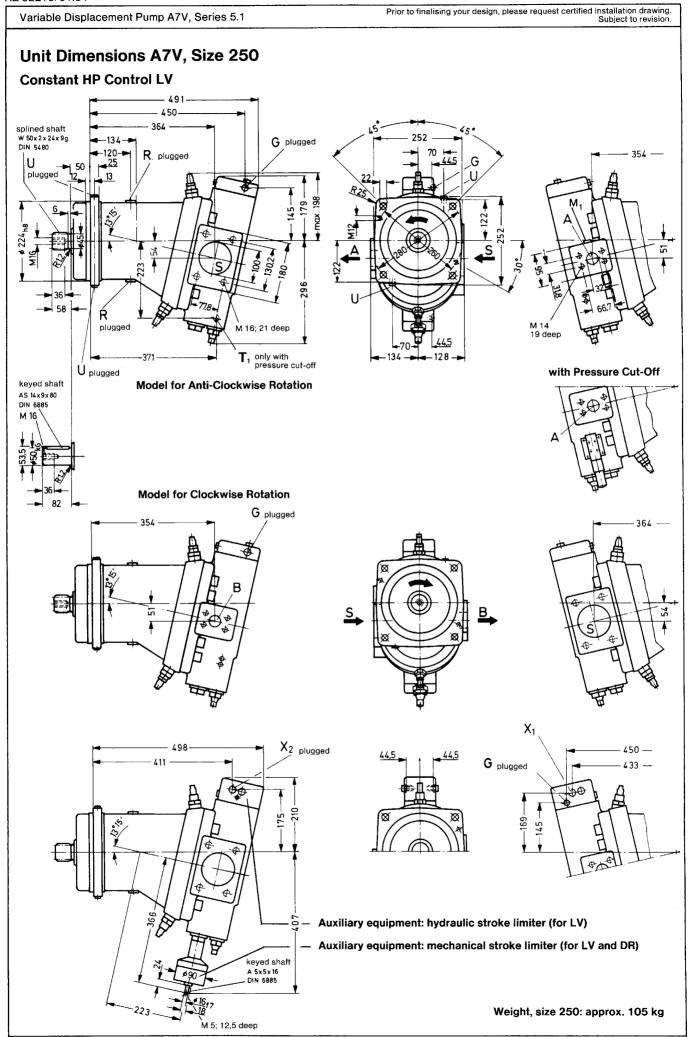
R air bleed

M₁ gauge connection

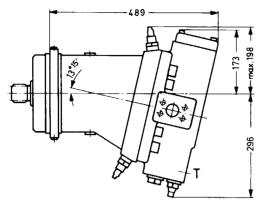
(operating pressure)

flushing port

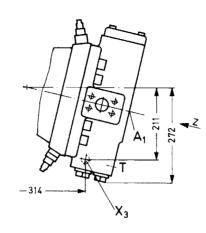
(for flushing of bearings)

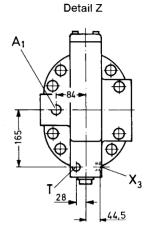


### **Standard Model**



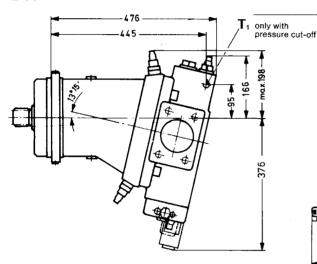
### **Remote Control**

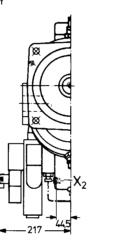


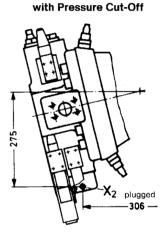


A<sub>1</sub> and X<sub>3</sub> only for remote control

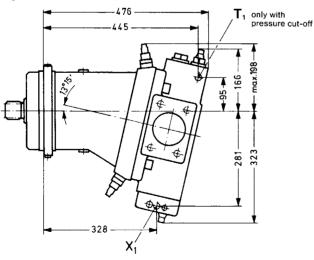
### **Electric Control EL**

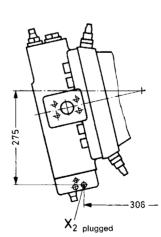






# Hydraulic Control, Pressure Related, HD







with Pressure Cut-Off

A,B	service lines
S	suction line
_	

remote control pressure G (connection for summation HP control)

 $X_1$ pilot pressure

remote control pressure  $X_2$ (HD, EL)

SAE 11/4" 420 bar (6000 psi) SAE 4" 35 bar (500 psi) M 14 x 1,5 (plugged)

 $M 14 \times 1,5$ M 14 x 1,5 (plugged) A<sub>1</sub>,X<sub>3</sub> ports for remote control valve

pilot oil return line Т  $\mathsf{T}_1$ pilot oil return line R air bleed U flushing port

(for flushing of bearings) gauge connection M<sub>1</sub> (operating pressure)

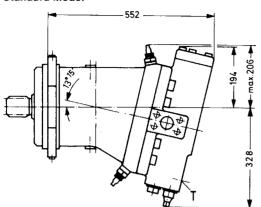
M 16 x 1,5

M 16 x 1,5 M 22 x 1,5

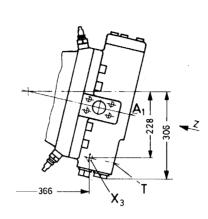
M 22 x 1,5 (plugged) M 14 x 1,5 (plugged)

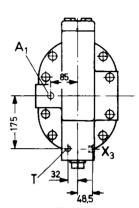
M 16 x 1,5 (plugged)

## Standard Model



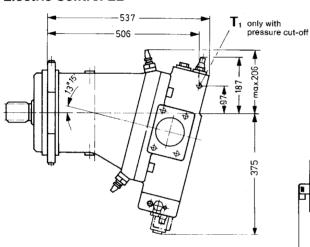
### **Remote Control**



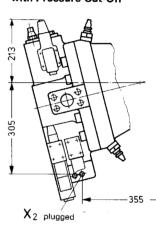


Detail Z

**Electric Control EL** 

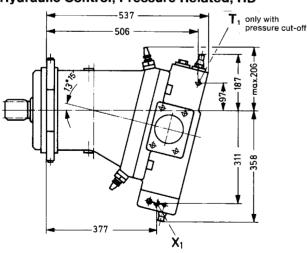


with Pressure Cut-Off

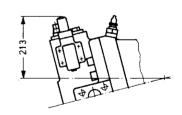


 $\boldsymbol{A_1}$  and  $\boldsymbol{X_3}$  only for remote control

# Hydraulic Control, Pressure Related, HD



-355 **—**  $X_2$  plugged



with Pressure Cut-Off

A,B	service lines
S	suction line
G	remote control pressure
	(connection for summation
	HP control)
Χ.	pilot pressure

X<sub>1</sub> remote control pressure (HD, EL)

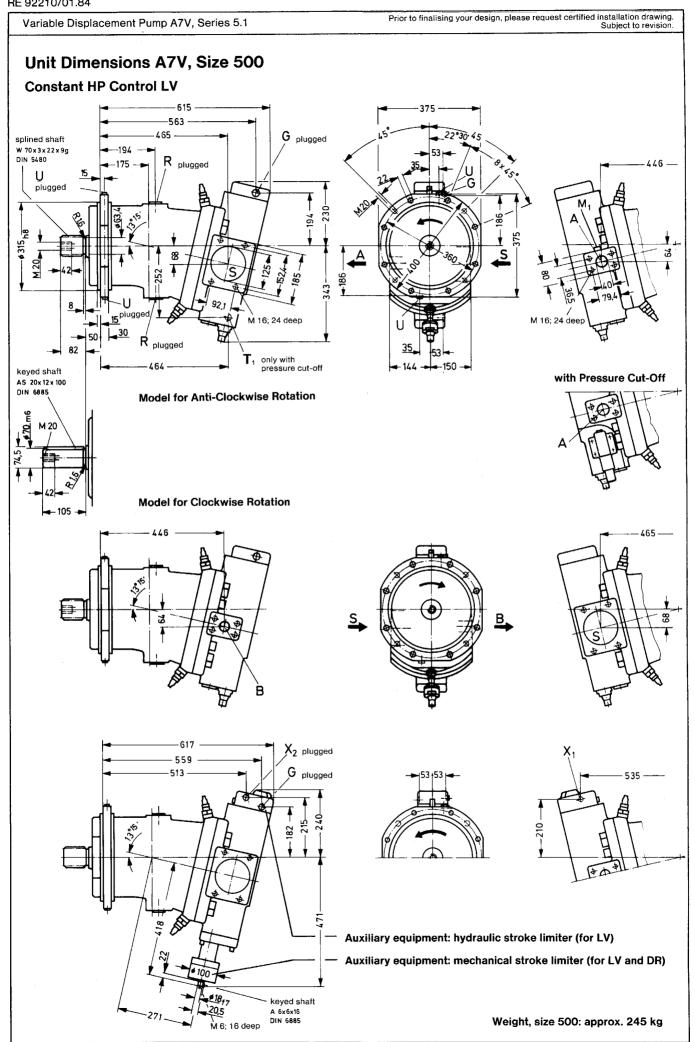
SAE 11/2" 420 bar (6000 psi) SAE 4" 35 bar (500 psi) M 16 x 1,5 (plugged)

M 16 x 1,5 M 16 x 1,5 (plugged)

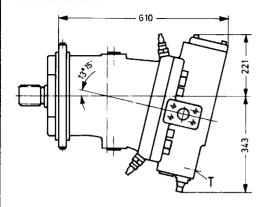
A<sub>1</sub>,X<sub>3</sub> ports for remote control valve pilot oil return line  $\mathsf{T}_1$ pilot oil return line R air bleed U flushing port М₁

(for flushing of bearings) gauge connection (operating pressure)

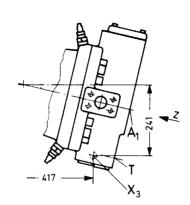
M 22 x 1,5 M 16 x 1,5 M 22 x 1,5 M 33 x 2 (plugged) M 14 x 1,5 (plugged) M 16 x 1,5 (plugged)

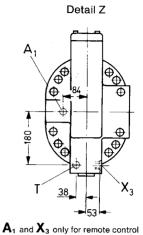


### Standard Model

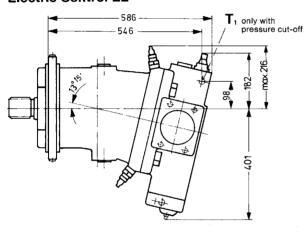


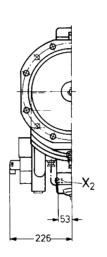
### **Remote Control**



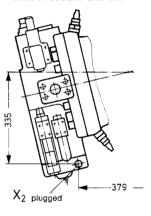


**Electric Control EL** 

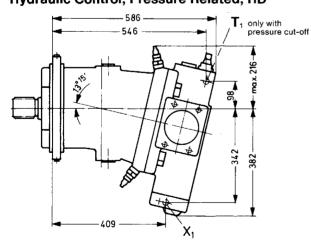


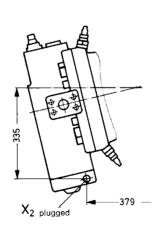


with Pressure Cut-Off



# Hydraulic Control, Pressure Related, HD





with Pressure Cut-Off



A,B S	service lines suction line
G	remote control pressure
	(connection for summation
	HP control)

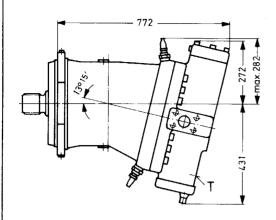
	111 001111017
$X_1$	pilot pressure
$X_2$	remote control pressure
	(HD, EL)

SAE 11/2" 420 bar (6000 psi)
SAE 5" 35 bar (500 psi)
M 16 x 1,5 (plugged)

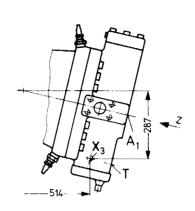
M 16 x 1,5	
M 16 x 1,5 (plugged)	

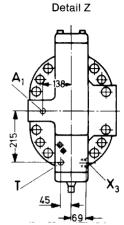
A <sub>1</sub> ,X <sub>3</sub>	ports for remote control valve	M 22 x 1,5
Т	pilot oil return line	M 16 x 1,5
$T_1$	pilot oil return line	M 22 x 1,5
R	air bleed	M 33 x 2 (plugged)
U	flushing port (for flushing of bearings)	M 18 x 1,5 (plugged)
M <sub>1</sub>	gauge connection (operating pressure)	M 16 x 1,5 (plugged)

# **Constant Pressure Control DR Standard Model**



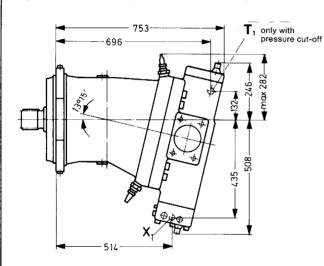
## **Remote Control**

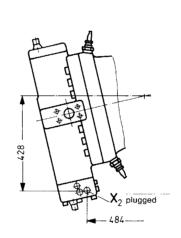




 $oldsymbol{A_1}$  and  $oldsymbol{X_3}$  only for remote control

# Hydraulic Control, Pressure Related, HD





with Pressure Cut-Off

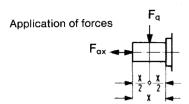


A,B S	service lines suction line	SAE 2" 420 bar (6000 psi) SAE 5" 35 bar (500 psi)
G	remote control pressure (connection for summation HP control)	M 22 x 1,5 (plugged)
$X_1$	pilot pressure	M 22 x 1,5
X <sub>2</sub>	remote control pressure (HD, EL)	M 22 x 1,5 (plugged)
A <sub>1</sub> ,X <sub>3</sub>	ports for remote control valve	M 22 x 1,5
T	pilot oil return line	M 16 x 1,5
T <sub>1</sub>	pilot oil return line	M 22 x 1,5
R	air bleed	M 42 x 2 (plugged)
U	flushing port (for flushing of bearings)	M 18 x 1,5 (plugged)
M <sub>1</sub>	gauge connection (operating pressure)	M 16 x 1,5 (plugged)

Variabel Displacement Pump A7V, Series 5.1

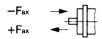
# **Drive**

The drive shaft has bearings which allow axial and radial forces to be absorbed. Such forces arise from gear or belt drives, etc.



### Permissible Axial Loads

The direction of axial force must be carefully noted.



The values for +Fax given below have no significant influence on the service life.

### Permissible axial force at operating pressure p = 1 bar abs.

Size	250	355	500	1000
Axial force – F <sub>ax</sub> (N)	1600	2000	2500	4000
Axial force + F <sub>ax</sub> (N)	4000	5000	6250	10000

### Permissible axial force at operating pressure p > 1 bar abs.

Size	250	355	500	1000	
Axial force + F <sub>ax</sub> (N)	4000	5000	6250	10000	
Constants K <sub>1</sub> (N/bar)	90	115	140	220	

A negative axial force - Fax is permissible, depending on operating pressure.

$$-F_{ax perm.} = -F_{ax} + K_1 \cdot p (N)$$

$$K_1 = constant \left(\frac{N}{bar}\right)$$

### **Permissible Radial Loads**

p = operating pressure (bar)

### At operating pressure p = 1 bar abs.

The radial load applied at the centre of the shaft length when the pump is stationary, or when it is rotating at zero pressure, may not exceed the value F<sub>q</sub>.

### At operating pressures p > 1 bar abs.

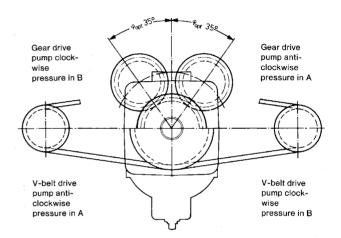
As the operating pressure is increased, higher radial forces are permissible on the drive shaft.

a) Gear drive (gear pressure angle to DIN 867) For direct gear drive, the values are given for a minimum pitch circle diameter  $D_{\text{R}\ \text{min}}$ , which are correct for forces in the centre of the drive shaft.

b) V-belt drive (narrow series to DIN 7753). The table shows the minimum permissible V-belt pulley diameters D<sub>K min</sub>, for forces applied to the centre of the drive shaft. Belt pre-tension should not exceed the value

Size	250	355	500	1000
F <sub>q</sub> (N)	2800	3500	4400	7000
D <sub>R min</sub> (mm) 1)	300	360	420	540
D <sub>K min</sub> (mm) <sup>1</sup> )	380	450	520	680

- 1) These will ensure that the service life of the units is not reduced, regardless of angle of application of radial force.
- c) Optimum direction of operation of the radial force



Provided that the optimum direction of operation of the radial force  $F_{\alpha 0}$  is maintained, the following values apply:

Size	250	355	500	1000
F <sub>q0</sub> (N)	4000	5000	6300	10000
D <sub>R0 min</sub> (mm)	150	180	210	270
D <sub>K0 min</sub> (mm)	250	300	350	450